





Daniel Condurache


Date of birth: 15/08/1955

Nationality: Romanian


CONTACT

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WORK EXPERIENCE

2012 – 2020

Vice-rector

“Gheorghe Asachi” Technical University of Iași, Romania
Informatization and digital communications

2005 – 2012

Head of Department

“Gheorghe Asachi” Technical University of Iași, Romania,
Department of Theoretical Mechanics

2001 – CURRENT

Professor (Emeritus 2022)

“Gheorghe Asachi” Technical University of Iași, Romania,
Department of Theoretical Mechanics

1996 – 2001

Associate professor

“Gheorghe Asachi” Technical University of Iași, Romania,
Department of Theoretical Mechanics

1990 – 1996

Lecturer

“Gheorghe Asachi” Technical University of Iași, Romania,
Department of Theoretical Mechanics

1984 – 1990

Assistant Professor

Polytechnic Institute of Iași, Department of Theoretical
Mechanics

EDUCATION AND TRAINING

1990 – 1995

PhD. Mechanical Engineering (Magna Cum Laude)

“Gheorghe Asachi” Technical University of Iași (Romania)
ISCED 4

1980 – 1985

Teacher of Mathematics

„Alexandru Ioan Cuza” University of Iași, Romania, Faculty
of Mathematics
ISCED 4

1975 – 1980

Engineer

Polytechnic Institute of Iași (Faculty of Electronics and Telecommunications)

ISCED 4

LANGUAGE SKILLS

MOTHER TONGUE(S): Romanian

OTHER LANGUAGE(S):

English

Listening B2	Reading C1	Spoken production B1	Spoken interaction B2	Writing B1
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French

Listening C2	Reading C2	Spoken production C1	Spoken interaction C1	Writing C1
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NETWORKS AND MEMBERSHIPS

Memberships

Senior Member AIAA (American Institute of Aeronautics and Astronautics) ID 268679

Senior Member IEEE (The Institute of Electrical and Electronics Engineers-USA) ID 80605322

Senior Member IEEE Robotics and Automation Society ID 80605322

Senior Member IEEE Aerospace and Electronic Systems Society ID 80605322

Member AAS (American Astronautical Society) ID 12690

Member ASME (American Society of Mechanical Engineering) ID 9012220

Member AMS (American Mathematical Society USA) code CNDCXK

Founding member of Romanian Society of Theoretical and Applied Mechanics

Corresponding member of the Academy of Technical Sciences in Romania

Corresponding member of the Romanian Academy

Member The New York Academy of Science ID 11012654

JOB-RELATED SKILLS

Job-related skills

- Algebraic and geometric methods in dynamic systems
- Astrodynamics, Satellites formation flying
- Orbital mechanics
- Integral transformations on hypercomplex spaces, wavelets analysis
- Lie group and Lie algebra in Robot computational kinematics and dynamics

- CNATDCU member - Mechanical Engineering, Mechatronics, and Robotics
- CCCDI member-Ministry of Research, Innovation, and Digitalization
- Ph.D. supervisor (Mechanical Engineering)

- Courses taught: Theoretical Mechanics, Technical Mechanics, Modeling and Simulation of Mechanical Systems, Mathematical Foundations of Robotics.

OTHER SKILLS

Other skills

1999 - present - Editor of the weekly newspaper *Opinia studentească* (both print and online)

Coordinator of the news agency *Cuzanet* (part of the *Alexandru Ioan Cuza University*) Courses taught: *Tehnici și tehnologii media*, *Multimedia și Canale media*, Department of Journalism and Communication Sciences, Faculty of Letters, "Al. I. Cuza" University of Iași

Author of over 300 articles (news, reportages, interviews, investigations etc.) published in *Viața Studentească*, *Opinia studentească*, *Europa Liberă*, *BBC*, *Expres Magazin*, *Evenimentul Zilei*

1996-1999 - general manager of the newspaper network *Monitorul*

1993-1996 - deputy editor *Evenimentul Zilei* 1992-1993 - department head *Evenimentul Zilei* 1992-1996 - department head *Expres Magazin* 1990-1992 - reporter *Europa Liberă*

1989-1992 - editor *Opinia studentească*

1982-1989 - deputy editor *Opinia studentească*

1975-1980 - deputy editor *Opinia studentească*

1974-1980 - deputy chief *Viața Studentească*

Founding member of Association of Journalists from Romania

Honorary president of Association of Professional Journalists from Iași

Member in the board of Center for Independent Journalism

Rotary International Public Image Coordinator - Evanston USA 2010-2014

District Governor Rotary International from Romania and Republic of Moldova 2009-2010

COD RESEARCHER

Cod Researcher

ID: B-7153-2011 6

H index 12

<https://publons.com/researcher/1423702/daniel-condurache/>

SCOPUS AUTOR

Scopus autor

ID: 15841500000

H index 13

<https://www.scopus.com/authid/detail.uri?authorId=15841500000>

ORCID

ORCID

ID: orcid.org/0000-0001-9287-8387

<https://orcid.org/0000-0001-9287-8387>

BOOKS AND CHAPTERS

Books and Chapters

Burlacu Adrian, **Condurache Daniel**, Corneliu Lazăr, *Motion Parameterization, and Control: Advances and Applications*, MATRIX ROM, 2021, ISBN 978-606-25-0653-7

Condurache D., *Singularity-Free Extraction of a Dual Quaternion from Orthogonal Dual Tensor*. Springer Proceedings in Advanced Robotics, vol 15. 2021, Springer, Cham. https://doi.org/10.1007/978-3-030-50975-0_18, ISBN 978-3-030-50974-3.

Condurache D., *Multidual Algebra and Higher-Order Kinematics*. New Trends in Mechanism and Machine Science. EuCoMeS 2020. Mechanisms and Machine Science, vol 89, 2020, Springer, Cham. https://doi.org/10.1007/978-3-030-55061-5_7, ISBN 978-3-030-55060-8

Condurache D. The Full-Body Kepler's Problem in a Non-Inertial Reference Frame. A Dual Lie Algebra Approach, **AAS 20-660**, July 2020, In book: Advances in the Astronautical Sciences, Edition: Vol 175, 2021, Chapter: AAS 20-660, Publisher: Univelt, Incorporated, P.O. Box 28130, San Diego, California 92198

Condurache D., *Higher-Order Kinematics of Rigid Bodies. A Tensors Algebra Approach*, In: Kecskeméthy A., Geu Flores F., Carrera E., Elias D. (eds) Interdisciplinary Applications of Kinematics. Mechanisms and Machine Science, vol 71. Springer, Cham, 2019, ISBN 978-3-030-16422-5

Condurache D., *Higher-Order Relative Kinematics of Rigid Body Motions: A Dual Lie Algebra Approach*, Advances in Robot Kinematics 2018. ARK 2018, Lenarcic J., Parenti-Castelli V. (eds), Vol 8. pg. 83-91, Springer Proceedings in Advanced Robotics, June 2018, ISBN 978-3-319-93188-3.

Condurache D., *On Six DOF Relative Orbital Motion of Satellites*, Space Flight, Pag. 78-100, June 20th, 2018, INTECH, ISBN: 978-1-78923-283-7.

Condurache, D., Ciureanu, I.-A., *Higher-order Cayley transforms for SE (3)*, Mechanisms and Machine Science, Volume 57, 2018, Pages 331-339, ISBN: 978-3-319-79110-4.

Condurache D., Burlacu A., *Recovering a Dual Euler Parameters from Feature-Based Representation of Motion*, Advances in Robot Kinematics, Jadran Lenarcic and Ousama Khatib (Eds), pp.295-305, Springer International, 2014, ISBN: 978-3-319-06697.

Condurache D., *Spacecraft Relative Orbital Motion*, Advances in Spacecraft Systems and Orbit Determination, Dr. Rushi Ghadawala (Ed.), Intech, 2012, ISBN: 978-953-51-0380-6.

Condurache D., *A New General investigation of the Kinematics of the Rigid Bodies*, Polirom, 2010, ISBN 973-9476-21-X

Condurache Daniel, *Capitole speciale de mecanică teoretică* – Iași : Polirom, 2010. ISBN: 973-9476-22-8

Condurache D., *Reprezentări simbolice. Aplicații în teoria semnalelor și studiul sistemelor dinamice (Symbolic Representations. Applications in Signal Theory and Dynamical Systems)*, Nord-Est, Iași, 1996, ISBN 973-97101-8-2.

Condurache, D., Matcovschi M. H., *Fundamentele matematice ale mecanicii roboților (Mathematical Fundamentals of Robot Mechanics)*, 2000

PUBLISHED RESEARCH ARTICLES

Published research articles

Over 100 articles published in research databases and ISI web of knowledge

ISI articles (selection)

Condurache, D.; Ciureanu, I.-A. *Baker–Campbell–Hausdorff–Dynkin Formula for the Lie Algebra of Rigid Body Displacements.* **Mathematics** 2020, 8, 1185.

Condurache D., *A Davenport dual angles approach for minimal parameterization of the rigid body displacement and motion,* **Mechanism and Machine Theory**, vol. 140, 2019, pp. 104-122.

Condurache D., *A MINIMAL PARAMETERIZATION ON SIX D.O.F. RELATIVE ORBITAL MOTION PROBLEM USING DUAL LIE ALGEBRA,* **Advances in the Astronautical Sciences**, Volume 167, 2019, pp. 783-800.

Condurache D., Burlacu A., *Fractional Order Cayley Transforms for Dual Quaternions based Pose Representation,* **Advances in the Astronautical Sciences**, Vol.165, 2016, pp. 1317-1339.

Condurache D., Burlacu A., *Onboard Exact Solution to the Full-Body Relative Orbital Motion Problem,* **AIAA Journal of Guidance, Control, and Dynamics**, Vol. 39, no.12, 2016, pp. 2638-2648.

Condurache D., Burlacu A., *Orthogonal dual tensor method for solving the $AX = XB$ sensor calibration problem,* **Mechanism and Machine Theory**, Vol 104, 2016, pp. 382-404.

Condurache D., Burlacu A., *Dual Tensors based Solutions for Rigid Body Motion Parameterization,* **Mechanism and Machine Theory**, Vol. 74, 2014, pp. 390-412.

Condurache, D.; Martinusi, V., *Quaternionic Exact Solution to the Relative Orbital Motion Problem,* **AIAA Journal of Guidance, Control, and Dynamics**, Vol. 33, no. 4, 2010, pp. 1035-1047.

Condurache, D., Martinusi, V., *Hypercomplex Eccentric Anomaly in the Unified Solution to the Relative Orbital Motion,* **Advances in the Astronautical Sciences**, Vol. 135, 2010, pp. 281-300. (AAS 09-321).

Condurache, D., Martinusi, V., *Exact Solution to the Relative Orbital Motion in Eccentric Orbits,* **Solar System Research**, Volume 43, Issue 1, 2009, pp. 41-52.

Condurache, D., Martinusi, V., *TOChNOERESHENIEZADACHl OTNOSITEL'NOGO ORBITAL'NOGO DVIZHENIYa PO EKSTsENTRICHESKOI ORBITE,* **Astronomicheskii Vestnik/Astronomy Review**, Vol. 43, No. 1, 2009, pp. 44-55.

Condurache D., Martinusi, V., *Foucault Pendulum-like problems: A Tensorial Approach,* **International Journal of Non-linear Mechanics**, vol. 43, issue 8, 2008, pp. 743-760.

Condurache D., Martinusi, V., *A Complete Closed Form Solution to the Kepler Problem,* **Meccanica**, Vol. 42, no.5, 2007, pp. 465-476.

Condurache D., Martinusi, V., *Relative Spacecraft Motion in a Central Force Field,* **AIAA Journal of Guidance, Control, and Dynamics**, vol. 30, no. 3, 2007, pp. 873-876.

Condurache D., Martinusi, V., *Kepler's Problem in Rotating Reference Frames. Part I : Prime Integrals, Vectorial Regularization,* **AIAA Journal of Guidance, Control and Dynamics**, Vol. 30, no. 1, 2007, pp. 192-200.

Condurache D., Martinusi, V., *Kepler's Problem in Rotating Reference Frames. Part II: Relative Orbital Motion,* **AIAA Journal of Guidance, Control and Dynamics**, Vol. 30, no. 1, 2007, pp. 201-213.

ARTICLES - INTERNATIONAL CONFERENCES PROCEEDINGS (SELECTION)

Articles - international conferences proceedings (selection)

Condurache D., *SINGULARITY-FREE EXTRACTION OF A DUAL QUATERNION FROM FEATURE-BASED REPRESENTATION OF MOTION*, **AAS/AIAA Astrodynamics Specialist Conference**, 11 - 15 August, 2019, Portland, USA

Condurache D., *Closed Form of the Baker-Campbell-Hausdorff Formula for the Lie Algebra of Rigid Body Displacements*, **ECCOMAS Multibody Dynamics Conference**, 15th - 18th July 2019, Duisburg, Germany

Condurache D., *A novel solution for $AX=YB$ sensor calibration problem using dual Lie algebra*, **6th International Conference on Control, Decision and Information Technologies (CODIT'19)**, April 2019, Paris, France

Condurache D., *Higher-Order Cayley Transform For Relative Pose Parameterization Of Spacecraft*, **69th International Astronautical Congress 2018**, Oct. 2018, Bremen, Germany.

Condurache D., *A Minimal Parameterization On Six D.O.F. Relative Orbital Motion Problem Using Dual Lie Algebra*, **AAS/AIAA Astrodynamics Specialist Conference** – Snowbird, August 19 – 23, 2018, UT, USA.

Condurache D., *Higher-order Rodrigues dual vectors. Kinematic equations and tangent operator*, **The 5th Joint International Conference on Multibody System Dynamics**, June 24 – 28, 2018, Lisbon, Portugal.

Condurache D., *Higher-Order Kinematics Of Rigid Bodies. A Tensors Algebra Approach*, **IAK 2018 – Third Conference on Interdisciplinary Applications in Kinematics**, March 5-7, 2018, Lima, Peru.

Condurache D., *On Board Complete Solution to the Full- Body Relative Orbital Motion Problem*, **68th International Astronautical Congress**, 25–29 September, 2017, Adelaide, Australia.

Condurache D., *Poisson-Darboux Problem's Extended in Dual Lie Algebra*, **AAS/AIAA Astrodynamics Specialist Conference**, August, 20-24, 2017, Columbia River Gorge, Stevenson, WA, USA.

Condurache D., Burlacu A., *General rigid body motion parameterization using modified Cayley transform for dual tensors and dual quaternions*, **The 4th Joint International Conference on Multibody System Dynamics**, May 29 - June 2, 2016, Montreal, Canada.

Condurache D., *Relative Orbital Motion Analysis using Dual Lie Algebra Representation*, **66th International Astronautical Congress (IAC) 2015: Space - The Gateway for Mankind's Future**, IAC 2015; Jerusalem; Israel; 12 October 2015-16 October 2015; Code 122921, pp. 6097-6100.

Condurache D., Burlacu A., *On Board Exact Solution to the Full Body Relative Orbital Motion Problem*, **AIAA Space and Astronautics Forum and Exposition: AIAA/AAS Astrodynamics Specialist Conference**, 4-7 August 2014, San Diego, USA.

Condurache D., Burlacu A., *On Six D.O.F Relative Orbital Motion Parameterization using Rigid Bases of Dual Vectors*, **AAS/AIAA Astrodynamics Specialist Conference**, Hilton Head, South Carolina, August 11-15, 2013.

Condurache, D., Burlacu A., *Rigid Body Pose Estimation using Dual Quaternions Computed from Direct Measurements*, **43rd International Symposium on Robotics**, May 29-31, Taiwan, Taipei, 2012.

RESEARCH GRANTS (SELECTION)

Research grants (selection)

2021: Principal Investigator POC/398/1/1-Cod SMIS 2014+124998

2019: Principal Investigator CNFIS-FDI- 2019-0273
"CONNECT@TUIASI: Infrastructura Wireless Smart Campus pentru susținerea procesului didactic și de cercetare și asigurarea securității cibernetice a comunicațiilor

2018-2019: Principal Investigator CNFIS-FDI-2018-0570 WIRELESS-CAMPUS: Extinderea infrastructurii wireless Smart Campus pentru susținerea activităților didactice și de cercetare

2018: CNFIS-FDI-2018-0006 Acces Direct prin Internaționalizarea Digitală- DIGITAL în TUIAȘI

2018: CNFIS-FDI-2018-0351 Instrumente pentru susținerea cercetării de excelență la TUIASI-Expert

2017-2018: Principal Investigator CNFIS-FDI-2016-0047 Implementarea Registrului Matricol Unic în Universitatea Tehnică "Gheorghe Asachi" din Iasi – RMU-TUIASI

2015-2016: CNFIS-FDI-2016-0047 Implementarea Registrului Matricol Unic în Universitatea Tehnică "Gheorghe Asachi" din Iasi – RMU-TUIASI

2014: PROIECT COMMIT-Expert

2014-2015: POSDRU/155/1.2/S/141884 ACAD-INOV "Comunitate virtuală pentru asigurarea calității și perfecționării managementului strategic și inovativ în universitățile tehnice și compozite, în vederea creșterii relevanței învățământului superior pentru piața muncii"

2007-2009: Principal Investigator: *Exact solutions in relative orbital dynamics. Applications in formation flying spacecraft guidance and control* (CNCSIS code 200).

2006: *Susținerea integrării cercetării românești în domeniul poluării electromagnetice în rețele, programe și parteneriate europene de profil (Supporting the Integration of Romanian Research in Electromagnetic Pollution in European networks, programs and partnerships), CEEX 2006.*

- **1998-2002: Director de proiect:** Noi modele pentru medii continuu deformabile și aplicații la interacțiunea dintre mediile compozite, granulare, viscoelastice și structura, (CNCSIS code 8, Grant tip 4C — Banca Mondială și Guvernul României, number 46769/1998).
- **1996:** Metode numerice de identificare și optimizare în studiul sistemelor dinamice.
- Faza 50.1: Studiarea, determinarea și optimizarea parametrilor constructivi și funcționali ai unor sisteme mecanice și caracteristici ale structurilor (Contract nr. 5002/1996, Tema 50/ Grant 498).
- **1994-1996:** Studiul vibrațiilor sistemelor mecanice cu aplicații în construcția de mașini.
- Faza de execuție: Condițiile de apariție a efectelor oscilațiilor neliniare în funcționarea mașinilor (Contract nr. 5002, Grant nr. 497, Tema nr. 49, 1996).
- Faza III: Modelarea matematică a fenomenelor specifice de vibrații neliniare ce intervin în diverse clase de mașini (Contract nr. 4002, Tema A23, grant nr. 761, 1995).
- Faza II: Aspecte noi în teoria modelării, identificării și optimizării sistemelor mecanice și structurilor (Contract nr. 4002/1995, Tema B22, grant nr. 765, 1995).
- Faza I: Studiu monografic și cercetări preliminare privind vibrațiile în construcția de mașini (Contract nr. 4002, Tema A23, grant nr. 761, 1994).

CONFERENCES (SELECTION)

Conferences (selection)

Relative Orbital Motion Analysis Using Dual Lie Algebra Representations, 66th International Astronautical Congress 2015, Astrodynamics Symposium, 12-16 October 2015, Jerusalem, Israel.

Fractional Order Cayley Transforms For Dual Quaternions Based Pose Representation, AAS/AIAA Astrodynamics Specialist Conference, 9-13 August 2015, Vail, Colorado, USA.

On Board Exact Solution to the Full Body Relative Orbital Motion Problem, AIAA Space and Astronautics Forum and Exposition: AIAA/AAS Astrodynamics Specialist Conference, 4-7 August 2014, San Diego, USA.

Dual Lie Algebra Representations of the Rigid Body Motion, AIAA Space and Astronautics Forum and Exposition: AIAA/AAS Astrodynamics Specialist Conference, 4-7 August 2014, San Diego, USA.

Recovering Dual Euler Parameters from Feature-Based Representation of Motion, 14th Int. Symposium on Advances in Robot Kinematics, June 29 – July 3, 2014, Ljubljana, Slovenia.

Analytical Orbit Propagator Based on Vectorial Orbital Elements, AIAA Guidance, Navigation and Control Conference, 19-21 August 2013, Boston, MA, USA. Paper AIAA-2013-5188.

On Six D.O.F Relative Orbital Motion Parametrization using Rigid Bases of Dual Vectors, AAS/AIAA Astrodynamics Specialist Conference, Hilton Head, South Carolina, USA, August 11-15, 2013.

Rigid Body Pose Estimation using Dual Quaternions Computed from Direct Measurements, 43rd International Symposium on Robotics, 29-31 May, Taiwan, Taipei, 2012.

Super-integrability in the unperturbed relative orbital motion problem, AIAA/AAS Astrodynamics Specialist Conference, Toronto, Canada, 2-5 August 2010.

Analytic Solution to the Relative Orbital Motion Around an Oblate Planet, AIAA Guidance, Navigation and Control Conference and Exhibit, Chicago, Illinois, USA, 10-13 Aug. 2009.

Hypercomplex Eccentric Anomaly in the Unified Solution to the Relative Orbital Motion; AAS/AIAA Astrodynamics Specialist Conference, Pittsburgh, Pennsylvania, USA, August 2009 (paper AAS-09-321).

Analytic Solution to the Relative Orbital Motion Around an Oblate Planet; AIAA Guidance, Navigation and Control Conference and Exhibit, Chicago, Illinois, August 2009 (paper AIAA 2009-6098).

Exact Solutions in Relative Orbital Dynamics; 3rd International Conference on Computational mechanics and virtual engineering, COMEC, Brasov, October 2009.

A Quaternionic Exact Solution to the Relative Orbital Motion, AIAA/AAS; Astrodynamics Specialist Conference and Exhibit, Honolulu, Hawaii, 18-21 August 2008, AIAA Paper 2008-6764.

Exact Solution to the Relative Orbital Motion in a Central Force Field; The 2nd IEEE/AIAA International Symposium on Systems and Control in Aeronautics and Astronautics, Shenzhen, China, 10-12 December 2008.

Exact Solution to the Relative Orbital Motion in Eccentric Orbits; International Conference "Analytical Methods of Celestial Mechanics", Sankt-Petersburg, Russia, July 2007.

A Novel Hypercomplex Solution to Kepler's Problem, PADEU, Astronomy Department. of the Eötvös University, 19, June 2007.

SCIENTIFIC ADVISOR

Scientific advisor

Acta Astronautica
Advances in Applied Clifford Algebras
Advances in Space Research
Aerospace Science and Technology
Antimicrobial Agents and Chemotherapy
Astrophysics and Space Science
Celestial Mechanics and Dynamical Astronomy
Heliyon
IEEE Robotics & Automation Letters
Information and Computation
International Journal of Non-linear Mechanics
Journal of Guidance, Control, and Dynamics
Journal of Mechanical Design
Journal of the Franklin Institute
Mathematical Methods in the Applied Sciences
Mathematical Problems in Engineering
Mathematics
Meccanica
Measurement
Mechanical Sciences
Mechanism and Machine Theory
Oyo rikigaku ronbunshu
Proceedings of the Royal Society A: Mathematical, Physical and Engineering Sciences
Robotica
Symmetry
Physics
The Journal of the Astronautical Sciences

International Advisory Committee

Bulletin of the Polytechnic Institute of Iași ISSN 1223-8139

Editor in Chief

ROMANIAN JOURNAL OF TECHNICAL SCIENCES - APPLIED MECHANICS ISSN 2601-5811

International Advisory Committee

Parana Journal of Science and Education (PJSE), ISSN 2447-6153

Member of the editorial team

Romanian Journal of Mechanics ISSN 2537 -5229

Editorial board member

Mechanical Sciences ISSN 2191-9151

Topical editor for Robotics, Dynamics, and Control

HONOURS AND AWARDS

Honours and awards

Academy of Technical Sciences in Romania Award "Constantin C. Teodorescu"- 22 October 2021

Romanian Academy Award "Traian Vuia" -12 December 2019

Doctor Honoris Causa of „Dunărea de Jos” University of Galați, 14 October 2016

Honorary citizen of Iași town - 14 October 2014

Winner of the Romanian Press Club Gala - 2003, for best editorial project

Iasi, 14/01/2023



Daniel Condurache